# POWERS $\boldsymbol{X}^{N}$ IN TERMS OF MODIFIED CHEBYSHEV POLYNOMIALS 

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#### Abstract

We exhibit two procedures to express $x^{n}$ in terms of the shifted Chebyshev polynomials, which is useful to reduce the degree of a polynomial in the interval $[0,1]$.


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## INTRODUCTION

In numerical analysis may be necessary to reduce, with small error, the degree of a polynomial in the interval $[0,1]$, which is possible employing the Modified Chebyshev polynomials $\bar{T}_{r}(x)$ defined by [1]:

$$
\begin{equation*}
\bar{T}_{0}(x)=\frac{1}{2}, \quad \bar{T}_{k}(x)=T_{k}(2 x-1), \quad k=1,2, \ldots \tag{1}
\end{equation*}
$$

where the first-kind Chebyshev polynomials $\bar{T}_{r}(x)$ are given by the recurrence relation [2-6]:

$$
\begin{equation*}
T_{0}(x)=1, \quad T_{1}(x)=x, \quad T_{k+1}(x)=2 x T_{k}(x)-T_{k-1}(x), \quad k=1,2, \ldots \tag{2}
\end{equation*}
$$

therefore

$$
\begin{array}{ll}
\bar{T}_{0}(x)=\frac{1}{2}, \quad \bar{T}_{1}(x)=2 x-1, & \bar{T}_{2}(x)=8 x^{2}-8 x+1,  \tag{3}\\
\bar{T}_{3}(x)=32 x^{3}-48 x^{2}+18 x-1, & \bar{T}_{4}(x)=128 x^{4}-256 x^{3}-32 x+1, \quad \text { etc. }
\end{array}
$$

In the mentioned reduction process we need the powers $x^{n}$ in terms of $\bar{T}_{r}$, then from (3):

$$
\begin{array}{ll}
x^{0}=2 \bar{T}_{0}, \quad x=\frac{1}{2}\left(2 \bar{T}_{0}+\bar{T}_{1}\right), & x^{2}=\frac{1}{8}\left(6 \bar{T}_{0}+4 \bar{T}_{1}+\bar{T}_{2}\right), \\
x^{3}=\frac{1}{32}\left(20 \bar{T}_{0}+15 \bar{T}_{1}+6 \bar{T}_{2}+\bar{T}_{3}\right), & x^{4}=\frac{1}{128}\left(70 \bar{T}_{0}+56 \bar{T}_{1}+28 \bar{T}_{2}+8 \bar{T}_{3}+\bar{T}_{4}\right), \quad \text { etc. } \tag{4}
\end{array}
$$

that is [1]:

$$
\begin{equation*}
\frac{1}{2}(4 x)^{n}=\sum_{r=0}^{n}\binom{2 n}{n-r} \bar{T}_{r}, \quad n=0,1, \ldots \tag{5}
\end{equation*}
$$

The next section exhibits an algorithm to obtain $x^{j}$ in function of $\bar{T}_{r}$ if we know the corresponding expansion of $x^{j-1}$, and also another procedure which employs to (5) as a Newton's binomial expression.

## $\boldsymbol{x}^{\boldsymbol{n}}$ in terms of $\bar{T}_{r}$

We may write (5) in the form:

$$
\begin{array}{ccccccc} 
& \bar{T}_{0} & \bar{T}_{1} & \bar{T}_{2} & \bar{T}_{3} & \bar{T}_{4} & \cdots \\
\frac{1}{2}(4 x)^{0} & 1 & 0 & 0 & 0 & 0 & \cdots \\
\frac{1}{2}(4 x)^{1} & 2 & 1 & 0 & 0 & 0 & \cdots \\
\frac{1}{2}(4 x)^{2} & 6 & 4 & 1 & 0 & 0 & \cdots  \tag{6}\\
\frac{1}{2}(4 x)^{3} & 20 & 15 & 6 & 1 & 0 & \cdots \\
\frac{1}{2}(4 x)^{4} & 70 & 56 & 28 & 8 & 1 & \cdots \\
\vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots
\end{array}
$$

or in function of the columns vectors $\left(\frac{1}{2}(4 x)^{j}\right)$ and $\left(\bar{T}_{r}\right)$ for a given $n$ :

$$
\left(\begin{array}{c}
\frac{1}{2}(4 x)^{0}  \tag{7}\\
\frac{1}{2}(4 x)^{1} \\
\vdots \\
\frac{1}{2}(4 x)^{n}
\end{array}\right)=\underset{\sim}{A} \cdot\left(\begin{array}{c}
\bar{T}_{0} \\
\bar{T}_{1} \\
\vdots \\
\bar{T}_{n}
\end{array}\right)
$$

where $A$ is the $(n+1) \times(n+1)$ triangular matrix of coefficients appearing in (6):

$$
\underset{\sim}{A}=\left(a_{j r}\right)=\left(\begin{array}{cccccc}
1 & 0 & 0 & 0 & 0 & \cdots  \tag{8}\\
2 & 1 & 0 & 0 & 0 & \cdots \\
6 & 4 & 1 & 0 & 0 & \cdots \\
20 & 15 & 6 & 1 & 0 & \cdots \\
70 & 56 & 28 & 8 & 1 & \cdots \\
\vdots & \vdots & \vdots & \vdots & \vdots & \ddots
\end{array}\right), \quad j, r=0,1, \ldots n
$$

then $\left(\bar{T}_{r}\right)=\underset{\sim}{A^{-1}} \cdot\left(\frac{1}{2}(4 x)^{r}\right)$ reproduces (3).
The relations (5) and (7) imply that:

$$
\begin{equation*}
a_{j r}=\binom{2 n}{n-r}, \quad j, r=0,1, \ldots \tag{9}
\end{equation*}
$$

thus

$$
\begin{equation*}
a_{j j}=1, \quad a_{j r}=0, \quad r>j \tag{10}
\end{equation*}
$$

and we can prove the following properties not found explicitly in the literature:

$$
\begin{align*}
& a_{j+1,0}=2\left(a_{j 0}+a_{j 1}\right), \quad j=0,1,2, \ldots \\
& a_{j r}=a_{j-1, r-1}+2 a_{j-1, r}+a_{j-1, r+1}, \quad r, j=1,2,3, \ldots \tag{11}
\end{align*}
$$

The formulae (11) permit to construct the row $j$ of $A$ if we know its row $j-1$, and they represent an algorithm to express $x^{n}$ in terms of $\left(\bar{T}_{r}\right)$ whose systematic use minimize the amount of arithmetical computations involved in (5).

On the other hand, the expansion (5) can be written as:

$$
\begin{equation*}
\frac{1}{2}(4 x)^{n}=\sum_{k=0}^{n}\binom{2 n}{k} \bar{T}_{n-k}=\sum_{k=0}^{2 n}\binom{2 n}{k} \bar{T}^{n-k} \tag{12}
\end{equation*}
$$

where we use the notation:

$$
\begin{equation*}
\bar{T}^{-j}=0, \quad j=1,2, \ldots, \quad \bar{T}^{r} \equiv \bar{T}_{r}, \quad r=0,1,2, \ldots \tag{13}
\end{equation*}
$$

very employed in Gregory-Newton and Stirling interpolations [7].

Thus (12) adopts the form of a Newton's binomial expression:

$$
\begin{equation*}
\frac{1}{2}(4 x)^{n}=\frac{1}{\bar{T}^{n}} \sum_{k=0}^{2 n}\binom{2 n}{k} \bar{T}^{2 n-k}=\frac{1}{\bar{T}^{n}}(1+\bar{T})^{2 n} \tag{14}
\end{equation*}
$$

which is a procedure alternative to (11) to obtain $x^{n}$ in function of $\bar{T}_{r}$. For example:

$$
\begin{aligned}
& \frac{1}{2}(4 x)^{2}=\frac{1}{\bar{T}^{2}}(1+\bar{T})^{4}=\frac{1}{\bar{T}^{2}}\left(1+4 \bar{T}+6 \bar{T}^{2}+4 \bar{T}^{3}+\bar{T}^{4}\right), \\
& =\bar{T}^{-2}+4 \bar{T}^{-1}+6 \bar{T}^{0}+4 \bar{T}+\bar{T}^{2}=6 \bar{T}_{0}+4 \bar{T}_{1}+\bar{T}_{2}, \quad \text { etc. }
\end{aligned}
$$

in according with (6). The relation (14) may be easily manipulated by a computer via some symbolic language as MAPLE.

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