Abstract: In this article, we establish some coincidence points and common fixed point results on integral and rational type contractive conditions using E.A. and common limit range (CLR) properties in dislocated metric space.

Keywords: Dislocated metric, Common fixed point, Weakly compatible maps.

Mathematics Subject Classification: 47H10, 54H25.

1. Introduction
In 1922, S. Banach [2] established a fixed point theorem in complete metric space, which is famous now as Banach contraction principle. This principle has been generalized and extended by several authors and has wide applications in the field of pure and applied mathematics. In 2000, P. Hitzler and A.K. Seda [4] obtained a generalization of topology which they named as dislocated topology. The corresponding generalized notion of metric was the dislocated metric. The concept of dislocated metric space was appeared in [8] by S. G. Matthews in 1986 under the name of metric domains. In 2002, A. Branciari [3] obtained a fixed point theorem for a map satisfying contractive condition of integral type with a summable Lebesgue integrable mapping in a complete metric space has been an interesting area of research. B.E. Rhoades [9] extended the theorem of Bancheri [3] with a most general contractive condition.

The purpose of this paper is to establish some results for integral and rational type contractive conditions for two pairs of maps with E.A. property for coincidence point results and with CLR property for weakly compatible maps for common fixed point results. Our results extend some fixed point theorems in the literature in the setting of dislocated metric space.

2. Preliminaries
We start with the following definitions, lemmas and theorems.

Definition 1 [4] Let \( X \) be a non empty set and let \( d : X \times X \rightarrow [0, \infty) \) be a function satisfying the following conditions:

1. \( d(x, y) = d(y, x) \)
2. \( d(x, y) = d(y, x) = 0 \) implies \( x = y \).
3. \( d(x, y) \leq d(x, z) + d(z, y) \) for all \( x, y, z \in X \).

Then \( d \) is called dislocated metric (or d-metric) on \( X \) and the pair \((X, d)\) is called the dislocated metric space (or d-metric space).
Definition 2 [10] Let $A$ and $S$ be two self mappings defined on a metric space $(X,d)$. We say that the mappings $A$ and $S$ satisfy Common Limit Range Property (CLR$_A$) property if there exists a sequence \( \{x_n\} \subset X \) such that
\[
\lim_{n \to \infty} Ax_n = \lim_{n \to \infty} Sx_n = Ax
\]

Definition 3 [1] Let $A$ and $S$ be two self mappings defined on a metric space $(X,d)$. We say that the mappings $A$ and $S$ satisfy (E. A.) property if there exists a sequence \( \{x_n\} \subset X \) such that
\[
\lim_{n \to \infty} Ax_n = \lim_{n \to \infty} Sx_n = u \quad \text{for some} \quad u \in X.
\]

Definition 4 [6] Let $A$ and $S$ be mappings from a metric space $(X,d)$ into itself. Then, $A$ and $S$ are said to be weakly compatible if they commute at their coincident point; that is, $Ax = Sx$ for some $x \in X$ implies $ASx = SAx$.

3 Main Results:
Now we establish the following result to obtain coincidence point for the given two pairs of mappings using E. A. property.

Theorem 1 Let $(X,d)$ be a dislocated metric space. Let $A, B, S, T : X \to X$ satisfying the following conditions
\[
A(X) \subseteq S(X) \quad \text{and} \quad B(X) \subseteq T(X)
\]
\[
\int_0^d(Ax, By) \phi(t) dt \leq k \int_0^d(M(x, y)) \phi(t) dt, \quad k \in [0, \frac{1}{2}]
\]
where $\phi : \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that
\[
\int_0^\epsilon \phi(t) dt > 0 \quad \text{for each} \quad \epsilon > 0
\]
\[
M(x, y) = \{d(Tx, Sy)d(Tx, Ax) + d(Sy, Ax) + d(Tx, Sy) + d(Tx, Ax)
+ d(By, Sy) + d(Tx, By) + d(By, Sy)d(Ax, Sy)\}
\]
If the pairs $(A, T)$ or $(B, S)$ satisfy E. A. property and $T(X)$ is closed then

i) the maps $A$ and $T$ have a coincidence point

ii) the maps $B$ and $S$ have a coincidence point

Proof: Assume that the pair $(A, T)$ satisfy E.A. property, so there exists a sequence \( \{x_n\} \subset X \) such that
\[
\lim_{n \to \infty} Ax_n = \lim_{n \to \infty} Tx_n = u
\]
for some $u \in X$. Since $A(X) \subseteq S(X)$, so there exists a sequence \( \{y_n\} \subset X \) such that $Ax_n = Sy_n$. Hence,
\[
\lim_{n \to \infty} Ax_n = \lim_{n \to \infty} Sy_n = u
\]
From condition (2) we have
\[
\int_0^{d(Ax_n, By_n)} \phi(t) dt \leq k \int_0^{M(x_n, y_n)} \phi(t) dt
\]
where
\[
M(x_n, y_n) = \{d(Tx_n, Sy_n)d(Tx_n, Ax_n) + d(Sy_n, Ax_n) + d(Tx_n, Sy_n) + d(Tx_n, Ax_n)\}
\]
Since,
\[ \lim_{n \to \infty} d(Tx_n, Sy_n) = \lim_{n \to \infty} d(Tx_n, Ax_n) = \lim_{n \to \infty} d(Sy_n, Ax_n) = 0 \]
and
\[ \lim_{n \to \infty} d(By_n, Sy_n) = \lim_{n \to \infty} d(Tx_n, By_n) = d(By_n, u) \]
Therefore taking limit as \( n \to \infty \) in (7) we get
\[
\lim_{n \to \infty} \int_{0}^{d(Ax_n, By_n)} \phi(t)dt \leq \lim_{n \to \infty} k \int_{0}^{M(x_n, y_n)} \phi(t)dt
\leq 2k \lim_{n \to \infty} \int_{0}^{d(By_n, u)} \phi(t)dt
\]
that is
\[
\lim_{n \to \infty} \int_{0}^{d(u, By_n)} \phi(t)dt \leq 2k \lim_{n \to \infty} \int_{0}^{d(By_n, u)} \phi(t)dt
\]
which is a contradiction, since \( k \in [0, \frac{1}{2}] \).
Hence, \( \lim_{n \to \infty} By_n = u \). Now we have
\[
\lim_{n \to \infty} Ax_n = \lim_{n \to \infty} Tx_n = \lim_{n \to \infty} By_n = \lim_{n \to \infty} Sy_n = u
\]
Assume \( T(X) \) is closed, then there exits \( v \in X \) such that \( Tv = u \). We claim that \( Av = u \).
Now from condition (2) we have,
\[
\int_{0}^{d(Av, By_n)} \phi(t)dt \leq k \int_{0}^{M(v, y_n)} \phi(t)dt
\]
where
\[
M(v, y_n) = \{ d(Tv, Sy_n)d(Tv, Av) + d(Sy_n, Av) + d(Tv, Sy_n) + d(Tv, Av) + d(By_n, Sy_n) + d(Tv, By_n) + d(By_n, Sy_n)d(Av, Sy_n) \}
\]
Since,
\[
\lim_{n \to \infty} d(Sy_n, Av) = d(u, Av)
\]
\[
\lim_{n \to \infty} d(Tv, Sy_n) = \lim_{n \to \infty} d(By_n, Sy_n) = \lim_{n \to \infty} d(Tv, By_n) = 0
\]
So, taking limit as \( n \to \infty \) in (8), We conclude that
\[
\int_{0}^{d(Av, u)} \phi(t)dt \leq 2k \int_{0}^{d(u, Av)} \phi(t)dt
\]
which is a contradiction. Therefore \( d(Av, u) = 0 \implies Av = u \).
Hence,
\( Av = u = Tv \).  \( \square \)
This proves that \( v \) is the coincidence point of \( (A, T) \).
Similarly we can show that \( v \) is the coincidence point of the pair \( (B, S) \).
This completes the proof of our theorem.

On the light of the above theorem we can establish the following corollaries.
Corollary 1 Let \((X,d)\) be a dislocated metric space. Let \(A,B,S:X \to X\) satisfying the following conditions
\[
A(X) \subseteq S(X) \quad \text{and} \quad B(X) \subseteq S(X)
\]
\[
\int_0^{d(Ax,By)} \phi(t) dt \leq k \int_0^{M(x,y)} \phi(t) dt, \quad k \in \left[0, \frac{1}{2}\right)
\]
where \(\phi: \mathbb{R}^+ \to \mathbb{R}^+\) is a Lebesgue integrable mapping which is summable, non-negative and such that
\[
\int_0^\varepsilon \phi(t) dt > 0 \quad \text{for all} \quad \varepsilon > 0
\]
\[
M(x,y) = \{d(Sx,Sy)d(Sx,Ax) + d(Sy,Ax) + d(Sx,Sy) + d(Sx,Ax)
+ d(By,Sy) + d(Sx,By) + d(By,Sy)d(Ax,Sy)\}
\]
If the pairs \((A,S)\) or \((B,S)\) satisfy E. A. property and \(S(X)\) is closed then
i) the maps \(A\) and \(S\) have a coincidence point
ii) the maps \(B\) and \(S\) have a coincidence point

Corollary 2 Let \((X,d)\) be a dislocated metric space. Let \(A,S,T:X \to X\) satisfying the following conditions
\[
A(X) \subseteq S(X) \quad \text{and} \quad A(X) \subseteq T(X)
\]
\[
\int_0^{d(Ax,Ay)} \phi(t) dt \leq k \int_0^{M(x,y)} \phi(t) dt, \quad k \in \left[0, \frac{1}{2}\right)
\]
where \(\phi: \mathbb{R}^+ \to \mathbb{R}^+\) is a Lebesgue integrable mapping which is summable, non-negative and such that
\[
\int_0^\varepsilon \phi(t) dt > 0 \quad \text{for all} \quad \varepsilon > 0
\]
\[
M(x,y) = \{d(Tx,Sy)d(Tx,Ax) + d(Sy,Ax) + d(Tx,Sy) + d(Tx,Ax)
+ d(Ay,Sy) + d(Tx,Ay) + d(Ay,Sy)d(Ax,Sy)\}
\]
If the pairs \((A,T)\) or \((A,S)\) satisfy E. A. property and \(T(X)\) is closed then
i) the maps \(A\) and \(S\) have a coincidence point
ii) the maps \(A\) and \(T\) have a coincidence point

Corollary 3 Let \((X,d)\) be a dislocated metric space. Let \(A,S:X \to X\) satisfying the following conditions
\[
A(X) \subseteq S(X)
\]
\[
\int_0^{d(Ax,Ay)} \phi(t) dt \leq k \int_0^{M(x,y)} \phi(t) dt, \quad k \in \left[0, \frac{1}{2}\right)
\]
where \(\phi: \mathbb{R}^+ \to \mathbb{R}^+\) is a Lebesgue integrable mapping which is summable, non-negative and such that
\[
\int_0^\varepsilon \phi(t) dt > 0 \quad \text{for all} \quad \varepsilon > 0
\]
(11)
\[
M(x,y) = \{d(Sx,Sy)d(Sx,Ax) + d(Sy,Ax) + d(Sx,Sy) + d(Sx,Ax)
+ d(Ay,Sy) + d(Sx,By) + d(Ay,Sy)d(Ax,Sy)\}
\]
If the pair \((A,S)\) satisfy E. A. property and \(S(X)\) is closed then the maps \(A\) and \(S\) have a coincidence point.

Corollary 4 Let \((X,d)\) be a dislocated metric space. Let \(A,B,I:X \to X\) satisfying the following conditions
\[
A(X) \quad \text{and} \quad B(X) \subseteq I(X)
\]
Dinesh Panthi / Some Theorems on Integral and Rational Type Contractive Conditions in Dislocated

Corollary 1
Let \((X, d)\) be a dislocated metric space. Let 
\[ f_0^d(Ax, By) \phi(t) dt \leq k \int_0^1 f_0^M(x, y) \phi(t) dt, \quad k \in [0, \frac{1}{2}] \]

where \(\phi: \mathbb{R}^+ \to \mathbb{R}^+\) is a Lebesgue integrable mapping which is summable, non-negative and such that
\[ \int_0^\epsilon f_0^\epsilon \phi(t) dt > 0 \quad \text{for each} \quad \epsilon > 0 \]

\[ M(x, y) = \{d(x, y) + d(Ax, y) + d(x, y) + d(x, Ax) + d(By, y) + d(By, Ax)\} \]

If the pairs \((A, T)\) or \((B, S)\) satisfy E. A. property and \(T(X)\) is closed then
i) the maps \(A\) and \(T\) have a coincidence point
ii) the maps \(B\) and \(S\) have a coincidence point

Corollary 2
Let \((X, d)\) be a dislocated metric space. Let 
\[ f_0^d(Ax, By) \phi(t) dt \leq k \int_0^1 f_0^M(x, y) \phi(t) dt, \quad k \in [0, \frac{1}{11}] \]

where, 
\[ M(x, y) = \{d(Tx, Sy) + d(Tx, Ax) + d(Tx, Ax) + d(By, Sy) + d(Tx, By) + d(Sy, Ax) + d(By, Ax)\} \]

and \(\phi: \mathbb{R}^+ \to \mathbb{R}^+\) is a Lebesgue integrable mapping which is summable, non-negative and such that
\[ \int_0^\epsilon f_0^\epsilon \phi(t) dt > 0 \quad \text{for each} \quad \epsilon > 0 \]

Theorem 2
Let \((X, d)\) be a dislocated metric space. Let \(A, B, S, T: X \to X\) satisfying the following conditions
\[ A(X) \subseteq S(X) \quad \text{and} \quad B(X) \subseteq T(X) \]

\[ f_0^d(Ax, By) \phi(t) dt \leq k \int_0^1 f_0^M(x, y) \phi(t) dt, \quad k \in [0, \frac{1}{2}] \]

where,
\[ M(x, y) = \{d(Tx, Sy) + d(Tx, Ax) + d(Tx, Ax) + d(By, Sy) + d(Tx, By) + d(Sy, Ax) + d(By, Ax)\} \]

The pairs \((A, T)\) or \((B, S)\) satisfy (CLR)-property
2. The pairs \((A, T)\) and \((B, S)\) are weakly compatible

then
i) the maps \(A\) and \(T\) have a coincidence point
ii) the maps \(B\) and \(S\) have a coincidence point
iii) the maps \(A, B, S\) and \(T\) have an unique common fixed point.

Proof: Assume that the pair \((A, T)\) satisfy (CLR\(_a\)) property, so there exists a sequence \(\{x_n\} \in X\) such that
\[ \lim_{n \to \infty} Ax_n = \lim_{n \to \infty} T x_n = Ax \]

for some \(x \in X\). Since \(A(X) \subseteq S(X)\), so there exists a sequence \(\{y_n\} \in X\) such that \(\lim_{n \to \infty} Ax_n = \lim_{n \to \infty} Sy_n = Ax\). We show that
\[ \lim_{n \to \infty} B x_n = Ax \]

From condition (13) we have
\[ f_0^d(Ax_n, By_n) \phi(t) dt \leq k \int_0^1 f_0^M(x_n, y_n) \phi(t) dt, \]

where
Taking limit as \( n \to \infty \) in (18) we get
\[
\lim_{n \to \infty} \int_0^M d(x_n, y_n) \, \phi(t) \, dt \leq k \lim_{n \to \infty} \int_0^M f(x_n, y_n) \, \phi(t) \, dt.
\] (19)
Since
\[
\lim_{n \to \infty} d(x_n, y_n) = \lim_{n \to \infty} d(x_n, y_n) = \lim_{n \to \infty} d(y_n, x_n) = 0
\]
Hence we have
\[
\lim_{n \to \infty} \int_0^M f(x_n, y_n) \, \phi(t) \, dt \leq 2k \lim_{n \to \infty} \int_0^M f(x_n, y_n) \, \phi(t) \, dt
\]
which is a contradiction, since \( k \in [0, \frac{1}{11}] \).
Therefore,
\[
\lim_{n \to \infty} d(x_n, y_n) = 0 \implies \lim_{n \to \infty} y_n = x_n.
\]
Now we have
\[
\lim_{n \to \infty} x_n = \lim_{n \to \infty} x_n = \lim_{n \to \infty} y_n = \lim_{n \to \infty} y_n = x
\]
Assume \( A(X) \subseteq S(X) \), then there exits \( v \in X \) such that \( Ax = Sv \).
We claim that \( Bv = Sv \).
Now from condition (13)
\[
\int_0^M f(x_n, v) \, \phi(t) \, dt \leq k \int_0^M f(x_n, v) \, \phi(t) \, dt
\] (20)
where
\[
M(x, v) = \left\{ \frac{d(Tx, Sv) \, d(Tx, Ax)}{d(Tx, Bv)} + d(Tx, Sv) + d(Tx, Ax) + d(Bv, Sv) + d(Tx, Bv) + d(Sv, Ax) + \frac{d(Bv, Sv) \, d(Ax, Sv)}{d(Tx, Bv)} \right\}
\]
Since
\[
\lim_{n \to \infty} d(Tx, Bv) = d(Ax, Bv) = d(Sv, Bv)
\]
\[
\lim_{n \to \infty} d(Tx, Sv) = \lim_{n \to \infty} d(Tx, Ax_n) = \lim_{n \to \infty} d(Sv, Ax_n) = 0
\]
So, taking limit as \( n \to \infty \) in (20), we conclude that
\[
\int_0^M f(Sv, Bv) \, \phi(t) \, dt \leq 2k \int_0^M f(Sv, Bv) \, \phi(t) \, dt
\] (21)
which is a contradiction.
Hence \( d(Sv, Bv) = 0 \implies Sv = Bv \).
This proves that \( v \) is the coincidence point of the maps \( B \) and \( S \).
Therefore, \( Sv = Bv = Ax = w(Sv) \).
Since the pair \((B, S)\) is weakly compatible, so
\( BSv = SBv \implies Bw = Sw \).
Since \( B(X) \subseteq T(X) \) there exists a point \( u \in X \) such that \( Bv = Tu \). We show that
\( Tu = Au = w \).
From condition (13),
\[
\int_0^M f(Au, Bv) \, \phi(t) \, dt \leq k \int_0^M f(\mu, \nu) \, \phi(t) \, dt,
\]
where,
\[
M(u, v) = \left\{ \frac{d(Tu, Sv)d(Tu, Au)}{d(Tu, Bv)} + d(Tu, Sv) + d(Tu, Au) + d(Bv, Sv) \right. \\
+ d(Tu, Bv) + d(Sv, Au) + \frac{d(Bv, Sv)d(Au, Sv)}{d(Tu, Bv)} \right\} \\
= \{d(Bv, Au) + d(Bv, Bv) + d(Bv, Au) + d(Bv, Bv) \} \\
+ \{d(Bv, Bv) + d(Bv, Au) + d(Au, Bv) \} \\
= \{3d(Bv, Bv) + 4d(Bv, Au) \} \\
\leq 10 d(Bv, Au)
\]

\[
\therefore \int_{0}^{d(Au, Bv)} \phi(t)dt \leq k \int_{0}^{M(u, v)} \phi(t)dt \leq 10 k \int_{0}^{d(Au, Bv)} \phi(t)dt
\]
which is a contradiction. Hence \(d(Au, Bv) = 0 \Rightarrow Au = Bv\).

\[
\therefore Au = Bv = Tu = w
\]
This proves that \(u\) is the coincidence point of the maps \(A\) and \(T\).
Since the pair \((A, T)\) is weakly compatible so,
\[ATu = TAu \Rightarrow Aw = Tw\]
We show that \(Aw = w\).

From condition (13)
\[
\int_{0}^{d(Aw, w)} \phi(t)dt = \int_{0}^{d(Aw, Bv)} \phi(t)dt \leq k \int_{0}^{M(w, v)} \phi(t)dt,
\]
where
\[
M(w, v) = \left\{ \frac{d(Tw, Sv)d(Tw, Aw)}{d(Tw, Bv)} + d(Tw, Sv) + d(Tw, Aw) + d(Bv, Sv) \right. \\
+ d(Tw, Bv) + d(Sv, Aw) + \frac{d(Bv, Sv)d(Aw, Sv)}{d(Tw, Bv)} \right\} \\
= \{\frac{d(Aw, w)d(Aw, Aw)}{d(Aw, w)} + d(Aw, w) + d(Aw, Aw) + d(w, w) \} \\
+ \{d(Aw, w) + d(w, Aw) + \frac{d(w, w)d(Aw, w)}{d(Aw, w)} \} \\
= \{3d(Aw, w) + 2d(Aw, Aw) + 2d(w, w) \} \\
\leq 11 d(Aw, w)
\]
\[
\therefore \int_{0}^{d(Aw, w)} \phi(t)dt = \int_{0}^{d(Aw, Bv)} \phi(t)dt \leq k \int_{0}^{M(w, v)} \phi(t)dt \leq 11 k \int_{0}^{d(Aw, w)} \phi(t)dt,
\]
which is a contradiction.
Hence \(d(Aw, w) = 0 \Rightarrow Aw = w\). Similarly we obtain \(Bw = w\).

\[
\therefore Aw = Bw = Sw = Tw = w\]. This establishes that \(w\) is the common fixed point of four mappings \(A, B, S\) and \(T\).

**Uniqueness:**

let \(z(\neq w)\) be other common fixed point of the mappings \(A, B, S\) and \(T\), then by the condition (13)
\[
\int_{0}^{d(w, z)} \phi(t)dt = \int_{0}^{d(Aw, Bz)} \phi(t)dt \leq k \int_{0}^{M(w, z)} \phi(t)dt
\]
Dinesh Panthi / Some Theorems on Integral and Rational Type Contractive Conditions in Dislocated metric spaces

\[ M(w, z) = \left( \frac{d(Tw, Sz)d(Tw, Aw)}{d(Tw, Bz)} + d(Tw, Sz) + d(Tw, Aw) + d(Bz, Sz) \right) \]
\[ + d(Tw, Bz) + d(Sz, Aw) + \frac{d(Bz, Sz)d(Aw, Sz)}{d(Tw, Bz)} \]
\[ = \left( \frac{d(w, z)d(w, w)}{d(w, z)} + d(w, z) + d(w, w) + d(z, z) \right) \]
\[ + d(w, z) + d(z, w) + \frac{d(z, z)d(w, w)}{d(w, z)} \]
\[ = 3d(w, z) + 2d(w, w) + 2d(z, z) \leq 11d(w, z) \]

\[ \therefore \int_0^{d(w, z)} \phi(t)dt = \int_0^{d(Aw, Bz)} \phi(t)dt \leq k \int_0^{M(w, z)} \phi(t)dt \leq 11k \int_0^{d(w, z)} \phi(t)dt \]

which is a contradiction.

Hence, \( d(w, z) = 0 \implies w = z \). This establishes the uniqueness of the common fixed point.

Now, on the light of above theorem we can establish the following corollaries.

**Corollary 5** Let \( (X, d) \) be a dislocated metric space. Let \( A, B, S: X \to X \) satisfying the following conditions

\[ A(X) \subseteq S(X) \quad \text{and} \quad B(X) \subseteq T(X) \]

\[ \int_0^{d(Ax, By)} \phi(t)dt \leq k \int_0^{M(x, y)} \phi(t)dt, \quad k \in \left[ 0, \frac{1}{11} \right) \]

where,

\[ M(x, y) = \left\{ \frac{d(Sx, Sy)d(Sx, Ax)}{d(Sx, By)} + d(Sx, Sy) + d(Sx, Ax) + d(By, Sy) \right\} \]
\[ + d(Sx, By) + d(Sy, Ax) + \frac{d(By, Sy)d(Ax, Sy)}{d(Sx, By)} \]

and \( \phi: \mathbb{R}^+ \to \mathbb{R}^+ \) is a Lebesgue integrable mapping which is summable, non-negative and such that

\[ \int_0^\epsilon \phi(t)dt > 0 \quad \text{for each} \quad \epsilon > 0 \]

1. The pairs \( (A, S) \) or \( (B, S) \) satisfy (CLR)-property
2. The pairs \( (A, S) \) and \( (B, S) \) are weakly compatible
   then
   i) the maps \( A \) and \( S \) have a coincidence point
   ii) the maps \( B \) and \( S \) have a coincidence point
   iii) the maps \( A, B \) and \( S \) have an unique common fixed point.

**Corollary 6** Let \( (X, d) \) be a dislocated metric space. Let \( A, S, T: X \to X \) satisfying the following conditions

\[ A(X) \subseteq S(X) \quad \text{and} \quad A(X) \subseteq T(X) \]

\[ \int_0^{d(Ax, Ay)} \phi(t)dt \leq k \int_0^{M(x, y)} \phi(t)dt, \quad k \in \left[ 0, \frac{1}{11} \right) \]

where,
\[ M(x,y) = \left\{ \frac{d(Tx,Sy)d(Tx,Ax)}{d(Tx,Ay)} + d(Tx, Sy) + d(Tx, Ax) + d(Ay, Sy) + d(Tx, Ay) + d(Sy, Ax) + \frac{d(Ay, Sy)d(Ax, Sy)}{d(Tx, Ay)} \right\} \]

and \( \phi: \mathbb{R}^+ \to \mathbb{R}^+ \) is a Lebesgue integrable mapping which is summable, non-negative and such that
\[
\int_0^\infty \phi(t)dt > 0 \quad \text{for each} \quad \epsilon > 0
\]

1. The pairs \((A, T)\) or \((A, S)\) satisfy (CLR)-property
2. The pairs \((A, T)\) and \((A, S)\) are weakly compatible

Then
i) the maps \(A\) and \(T\) have a coincidence point
ii) the maps \(A\) and \(S\) have a coincidence point
iii) the maps \(A, S\) and \(T\) have an unique common fixed point.

**Corrollary 7** Let \((X,d)\) be a dislocated metric space. Let \(A, S: X \to X\) satisfying the following conditions
\[ A(X) \subseteq S(X) \]
\[ \int_0^\infty d(Ax, Ay) \phi(t)dt \leq k \int_0^\infty M(x, y) \phi(t)dt, \quad k \in [0, \frac{1}{11}] \]
where,
\[ M(x, y) = \left\{ \frac{d(Sx, Sy)d(Sx, Ax)}{d(Sx, Ay)} + d(Sx, Sy) + d(Sx, Ax) + d(Ay, Sy) + d(Sx, Ay) + d(Sy, Ax) + \frac{d(Ay, Sy)d(Ax, Sy)}{d(Sx, Ay)} \right\} \]

and \( \phi: \mathbb{R}^+ \to \mathbb{R}^+ \) is a Lebesgue integrable mapping which is summable, non-negative and such that
\[
\int_0^\infty \phi(t)dt > 0 \quad \text{for each} \quad \epsilon > 0
\]

1. The pair \((A, S)\) satisfy (CLR)-property
2. The pair \((A, S)\) is weakly compatible

then, the maps \(A\) and \(S\) have a coincidence point and an unique common fixed point.

**Corrollary 8** Let \((X,d)\) be a dislocated metric space. Let \(A, B, I: X \to X\) satisfying the following conditions
\[ A(X) \quad \text{and} \quad B(X) \subseteq I(X) \]
\[ \int_0^\infty d(Ax, By) \phi(t)dt \leq k \int_0^\infty M(x, y) \phi(t)dt, \quad k \in [0, \frac{1}{11}] \]
where,
\[ M(x, y) = \left\{ \frac{d(x, y)d(x, Ax)}{d(x, By)} + d(x, y) + d(x, Ax) + d(By, y) + d(x, By) + d(y, Ax) + \frac{d(By, y)d(Ax, y)}{d(x, By)} \right\} \]

and \( \phi: \mathbb{R}^+ \to \mathbb{R}^+ \) is a Lebesgue integrable mapping which is summable, non-negative and such that
\[
\int_0^\infty \phi(t)dt > 0 \quad \text{for each} \quad \epsilon > 0
\]

1. The pairs \((A, I)\) or \((B, I)\) satisfy (CLR)-property
2. The pairs \((A, I)\) and \((B, I)\) are weakly compatible

then
i) the maps \(A\) and \(I\) have a coincidence point
ii) the maps B and I have a coincidence point

iii) the maps A, B and I have an unique common fixed point.

Conclusion
In this article, we used the (E.A.) property to establish coincidence point results and CLR property to claim the existence of common fixed point results of some rational and integral type contraction for two pairs of weakly compatible mappings. Our theorems extend and generalize the theorems of A. Branciary [3], B.E. Rhoades [9], P.Vijayaraju et.al [11] and J. Kumar [7] in the setting of dislocated metric spaces.

Acknowledgment
This work is carried under the research project SRTDIP-76/77-S&T-09 supported by University Grants Commission, Nepal. The author expresses sincere thank to referees for their careful reading and valuable suggestions for the improvement of manuscript.

References


http://dx.doi.org/10.1155/S0161171202007524


http://dx.doi.org/10.1155/S0161171203208024


https://doi.org/10.1155/2011/637958