



# Three Dimensional Fractional Mellin Transform, and its Applications

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## Abstract

We introduce three dimensional fractional Mellin transform and establish analytic theorem, boundedness theorem, inversion theorem and uniqueness theorem for three dimensional fractional Mellin transform. We present propositions of 3-dimensional fractional Mellin transform. We give some applications of 3-dimensional fractional Mellin transform for solving PDE's.

**Keywords:** Three dimensional fractional Mellin transform; analytic theorem; boundedness theorem; uniqueness theorem; inversion theorem; Mboctara equation.

**AMS(MOS) Subject Classification:** 44A05, 44A15

## 1 Introduction

In modern era, the work of integral transform is very important in the daily life [1- 3]. In the present scenario, the fractional integral transform has been widely used in signal processing, image reconstruction, pattern recognition, and many more fields [4, 5]. Mellin transform is derived from a complex Fourier transform [1] called scale covariant transform [6,7]. Mellin

transform has many applications, such as algorithms, correlators, navigation, vowel recognition, cryptographic scheme quantum calculus, radar classification of ships, electromagnetic, stress distribution, agriculture, medical stream, statistics, probability, signal processing, optics, and pattern recognition [8, 9]. Akay and Boudreaux [7] have introduced the fractional Mellin transform to generalize the scale covariant transform. In connection with fractional order, the fractional Fourier transform was given by Namias [6], which was dependent on continuous parameters. The applications of fractional Mellin transform have been given in controlling the range of rotation and scaling of the signal system [2, 10,], whereas the fractional Fourier transform is only restricted to object recognition in the signal system [8,10-15]. So, the fractional Mellin transform is an essential aspect for analysis of the control system, stability of electrical networks, and many more in Science and Engineering. Sharma and Deshmukh [8] have given applications of two-dimensional fractional Mellin transform. To solve some kind of third-order differential equations is a challenging task [11]. In this context, we present propositions that extend the Mellin transform to a fractional form. We also explore the concept of 3-DFrMT to solve certain third- order homogeneous Mboctara PDE's. This work represents an original scientific contribution and introduces new findings in the field.

## 2 3-DFrMT

**Definition 2.1.** 3DFrMT with parameter  $\Lambda$  of  $h(z, w, \mathcal{U})$  denoted by 3DFrMT  $\{h(z, w, \mathcal{U})\}$  and it is defined by

$$3DFrMT\{h(z, w, \mathcal{U})\} = H_{\Lambda}(\beta, \gamma, \delta) = \int_0^{\infty} \int_0^{\infty} \int_0^{\infty} h(z, w, \mathcal{U}) K_{\Lambda}(z, w, \mathcal{U}, \beta, \gamma, \delta) dz dw d\mathcal{U} \quad (2.1)$$

where, the kernal

$$K_{\Lambda}(z, w, \mathcal{U}, \beta, \gamma, \delta) = z^{\frac{2\pi i\beta}{\sin \Lambda} - 1} w^{\frac{2\pi i\gamma}{\sin \Lambda} - 1} \mathcal{U}^{\frac{2\pi i\delta}{\sin \Lambda} - 1} e^{-\pi i \left[ \frac{1}{\tan \Lambda} (\beta^2 + \log^2 z) + \frac{1}{\tan \Lambda} (\gamma^2 + \log^2 w) + \frac{1}{\tan \Lambda} (\delta^2 + \log^2 \mathcal{U}) \right]}$$

for,  $0 < \Lambda \leq \frac{\pi}{2}$ .

Now we give the analytic theorem in 3DFrMT.

**Theorem 2.2.** Let  $h \in E^*(R^n)$  and its FrMT be defined by (5), then  $H_\Lambda(\chi, \zeta, \rho)$  is analytic on  $C^n$  if the  $\varpi, \tau, \kappa$   $\text{supp } h \subset S_\varpi, S_\tau$  and  $S_\kappa$ , where

$$S_\varpi = \{z : z \in R^n, |z| \leq \varpi, \varpi > 0\},$$

$$S_\tau = \{w : w \in R^n, |w| \leq \tau, \tau > 0\},$$

$$S_\kappa = \{\mathcal{U} : \mathcal{U} \in R^n, |\mathcal{U}| \leq \kappa, \kappa > 0\}.$$

Moreover  $H_\Lambda(\chi, \zeta, \rho)$  is differentiable and  $D_\beta^\chi D_\gamma^\zeta D_\delta^\rho H_\Lambda(\beta, \gamma, \delta) = \langle h(z, w, \mathcal{U}, \beta, \gamma, \delta) \rangle$

**Proof.** Let

$$\beta: (\beta_1, \beta_2, \dots, \beta_j, \dots, \beta_n) \in C^n,$$

$$\gamma: (\gamma_1, \gamma_2, \dots, \gamma_j, \dots, \gamma_n) \in C^n,$$

$$\delta: (\delta_1, \delta_2, \dots, \delta_j, \dots, \delta_n) \in C^n.$$

We first prove that

$$\frac{\partial}{\partial \beta_j} \frac{\partial}{\partial \gamma_j} \frac{\partial}{\partial \delta_j} H_\Lambda(\beta, \gamma, \delta) = \langle h(z, w, \mathcal{U}), \frac{\partial}{\partial \beta_j} \frac{\partial}{\partial \gamma_j} \frac{\partial}{\partial \delta_j} K_\Lambda(z, w, \mathcal{U}, \beta, \gamma, \delta) \rangle.$$

For fixed  $\beta_j \neq 0$ , choose two concentric circles  $C_1, C_2$  with centre at  $\sigma$  and radius  $R_1, R_2$  respectively such that  $0 < R_1 < R_2 < |\beta_j|$ . Let  $\Delta\beta_{i,j}$  be a complex increment satisfying

$$0 < |\beta_j| < R_1.$$

Again for fixed  $\gamma_j \neq 0$ . Again choose two concentric circles  $C_3, C_4$  with centre at  $\eta$  and radius  $R_3, R_4$  respectively such that  $0 < R_3 < R_4 < |\gamma_j|$ . Let  $\Delta\gamma_{i,j}$  be a complex increment satisfying  $0 < |\gamma_j| < R_3$ .

Also for fixed  $\delta_j \neq 0$ , choose two concentric circles  $C_5, C_6$  with centre at  $\iota$  and radius  $R_5, R_6$  respectively such that  $0 < R_5 < R_6 < |\delta_j|$ . Let  $\Delta\delta_{i,j}$  be a complex increment

satisfying  $0 < |\Delta\delta_j| < R_5$ .

$$\begin{aligned} \text{Consider } & \frac{H_\Lambda|(\beta_j + \Delta\beta_j), \gamma_j, \delta_j| - H_\Lambda|\beta_j, \gamma_j, \delta_j|}{\Delta\beta_j} - \frac{H_\Lambda|(\beta_j, (\gamma_j + \Delta\gamma_j), \delta_j| - H_\Lambda|\beta_j, \gamma_j, \delta_j|}{\Delta\gamma_j} \\ & \frac{H_\Lambda|\beta_j, \gamma_j, (\delta_j + \Delta\delta_j)| - H_\Lambda|\beta_j, \gamma_j, \delta_j|}{\Delta\delta_j} < h(z, w, \mathfrak{U}) \frac{\partial}{\partial\beta_j} \frac{\partial}{\partial\gamma_j} \frac{\partial}{\partial\delta_j} K_\Lambda(z, w, \mathfrak{U}, \beta, \gamma, \delta) > \\ & = < h(z, w, \mathfrak{U}), \Upsilon_{\Delta\beta_j\Delta\gamma_j\Delta\delta_j}(z, w, \mathfrak{U}) > \end{aligned} \quad (2.2)$$

$$K_\Lambda(z, w, \mathfrak{U}, \beta_j, \gamma_j, \delta_j).$$

We have,

$$\begin{aligned} & D_z^\chi D_w^\zeta D_{\mathfrak{U}}^\rho K_\Lambda(z, w, \mathfrak{U}, \beta, \gamma, \delta) \\ & = D_z^\chi D_w^\zeta D_{\mathfrak{U}}^\rho \left[ z^{\frac{2\pi i\beta}{\sin\Lambda} - 1} w^{\frac{2\pi i\gamma}{\sin\Lambda} - 1} \mathfrak{U}^{\frac{2\pi i\delta}{\sin\Lambda} - 1} e^{\pi i \left[ \frac{1}{\tan\Lambda}(\beta^2 + \log^2 z) + \frac{1}{\tan\Lambda}(\gamma^2 + \log^2 w) + \frac{1}{\tan\Lambda}(\delta^2 + \log^2 \mathfrak{U}) \right]} \right] \\ & = \sum_{A=0}^\chi \sum_{U=0}^A \sum_{B=0}^\zeta \sum_{R=0}^B \sum_{M=0}^\rho \sum_{L=0}^M \binom{\chi}{A} \binom{\zeta}{B} \binom{\rho}{M} E(\beta) \Omega(\gamma) T(\delta) A! B! M! z^{-\chi+U} w^{-\zeta+R} \mathfrak{U}^{-\rho+L} \\ & \quad \left( \frac{2\pi i}{\tan\Lambda} \right)^{A-U} \left( \frac{2\pi i}{\tan\Lambda} \right)^{B-R} \left( \frac{2\pi i}{\tan\Lambda} \right)^{M-L} (\log z)^{A-U} (\log w)^{B-R} (\log \mathfrak{U})^{M-L} C_U(z) C_R(w) \\ & \quad C_L(\mathfrak{U}) K_\Lambda(z, w, \mathfrak{U}, \beta, \gamma, \delta), \end{aligned}$$

where,  $E(\beta)$ ,  $\Omega(\gamma)$  and  $T(\delta)$  is a polynomials in  $\beta, \gamma, \delta$ .

Since  $z, w, \mathfrak{U} \in R^n$  and fixed  $\chi, \zeta, \rho$  and  $\Lambda$  are ranging from 0 to  $\frac{\pi}{2}$ ,

$D_z^\chi D_w^\zeta D_{\mathfrak{U}}^\rho K_\Lambda(z, w, \mathfrak{U}, \beta, \gamma, \delta)$  is analytic inside and on  $C''$ ,  $C_1''$  and  $C_2''$ , we have by Cauchy's integral formula

$$\begin{aligned} & D_z^\chi D_w^\zeta D_{\mathfrak{U}}^\rho \Upsilon_{\Delta\beta_j\Delta\gamma_j\Delta\delta_j}(z, w, \mathfrak{U}) \\ & = \frac{1}{8\pi^3 i^3} D_z^\chi D_w^\zeta D_{\mathfrak{U}}^\rho \int_{C''} \int_{C_1''} \int_{C_2''} K_\Lambda(z, w, \mathfrak{U}, \tilde{\beta}, \tilde{\gamma}, \tilde{\delta}) \left[ \frac{1}{\Delta\beta_j} \left( \frac{1}{X - \beta_j - \Delta\beta_j} - \frac{1}{X - \beta_j} \right) - \frac{1}{(X - \beta_j)^2} \right] \\ & \quad \left[ \frac{1}{\Delta\gamma_j} \left( \frac{1}{Y - \gamma_j - \Delta\gamma_j} - \frac{1}{Y - \gamma_j} \right) - \frac{1}{(Y - \gamma_j)^2} \right] \left[ \frac{1}{\Delta\delta_j} \left( \frac{1}{Z - \delta_j - \Delta\delta_j} - \frac{1}{Z - \delta_j} \right) - \frac{1}{(Z - \delta_j)^2} \right] dX dY dZ \end{aligned}$$

where,

$$\tilde{\beta} = \beta_1, \beta_2, \dots, \beta_{j-1}, X, \beta_{j+1}, \dots, \beta_n,$$

$$\tilde{\gamma} = \gamma_1, \gamma_2, \dots, \gamma_{j-1}, Y, \gamma_{j+1}, \dots, \gamma_n,$$

$$\tilde{\delta} = \delta_1, \delta_2, \dots, \delta_{j-1}, Z, \delta_{j+1}, \dots, \delta_n$$

$$= \frac{\Delta\beta_j \Delta\gamma_j \Delta\delta_j}{-8\pi^3 i} \int_{C''} \int_{C_1''} \int_{C_2''} \frac{T(z, w, \mathcal{U}, \tilde{\beta}, \tilde{\gamma}, \tilde{\delta})}{(X - \beta_j - \Delta\beta_j)(X - \beta_j)^2(Y - \gamma_j - \Delta\gamma_j)(Y - \gamma_j)^2 (Z - \delta_j - \Delta\delta_j)(Z - \delta_j)^2} dX dY dZ$$

But for all  $X \in C''$ ,  $Y \in C_1''$  and  $Z \in C_2''$  and  $z, w$  and  $\mathcal{U}$  restricted to a compact subset of  $R^n$ ,  $0 < \Lambda \leq \frac{\pi}{2}$ ,  $T(z, w, \mathcal{U}, \beta, \gamma, \delta) = D_z^X D_w^\zeta D_{\mathcal{U}}^\rho K(z, w, \mathcal{U}, \beta, \gamma, \delta)$  is bounded by a constant  $G$ .

Moreover  $|X - \beta_j - \Delta\beta_j| > R_2 - R_1 > 0$  and  $|X - \beta_j| = R_2$ ,  $|Y - \gamma_j - \Delta\gamma_j| > R_4 - R_3 > 0$  and

$$|Y - \gamma_j| = R_4, |Z - \delta_j - \Delta\delta_j| > R_6 - R_5 > 0 \text{ and } |Z - \delta_j| = R_6.$$

Therefore we have,

$$\begin{aligned} & \left| D_z^X D_w^\zeta D_{\mathcal{U}}^\rho \Upsilon_{\Delta\beta_j \Delta\gamma_j \Delta\delta_j}(z, w, \mathcal{U}) \right| \\ & \leq \frac{|\Delta\beta_j| |\Delta\gamma_j| |\Delta\delta_j|}{8\pi^3 i} \int_{C''} \int_{C_1''} \int_{C_2''} \frac{G}{(R_2 - R_1)R_2^2 (R_4 - R_3)R_4^2 (R_6 - R_5)R_6^2} |dX| |dY| |dZ| \\ & \leq \frac{|\Delta\beta_j| |\Delta\gamma_j| |\Delta\delta_j| G}{(R_2 - R_1)R_2 (R_4 - R_3)R_4 (R_6 - R_5)R_6} \end{aligned}$$

Thus, as  $|\Delta\beta_j| \rightarrow 0$ ,  $|\Delta\gamma_j| \rightarrow 0$  and  $|\Delta\delta_j| \rightarrow 0$ ,  $D_z^X D_w^\zeta D_{\mathcal{U}}^\rho \Upsilon_{\Delta\beta_j \Delta\gamma_j \Delta\delta_j}(z, w, \mathcal{U}) \rightarrow 0$  uniformly on the compact subset of  $R^n$ . Thus  $\Upsilon_{\beta_j, \gamma_j, \delta_j}(z, w, \mathcal{U})$  converges in  $E(R^n)$  to zero.

Since  $h \in (E^*)$ , therefore (6) is  $\rightarrow 0$ . Thus  $H_\Lambda(\beta, \gamma, \delta)$  is differentiable with respect to  $\beta_j, \gamma_j$  and  $\delta_j$ . But this is true for all  $i, j = 1, 2, \dots, n$ . Therefore,  $H_\Lambda(\beta, \gamma, \delta)$  is analytic on  $C^m$  and

$$D_\beta^X D_\gamma^\zeta D_\delta^\rho H_\Lambda(\beta, \gamma, \delta) = \langle h(z, w, \mathcal{U}, \beta, \gamma, \delta), D_\beta^X D_\gamma^\zeta D_\delta^\rho K_\Lambda(z, w, \mathcal{U}, \beta, \gamma, \delta) \rangle .$$

Now we give boundedness theorem in 3DFrMT.

**Theorem 2.3.** Let  $h(z, w, \mathfrak{U}) \in E^*(R^n)$  and its FrMT be defined by (2.3). Let  $\text{supp } h \subset s_{\varpi} \cup s_{\tau} \cup s_{\kappa}$ , where  $S_{\varpi} = \{z : z \in R^n, |z| \leq \varpi, \varpi > 0\}$ ,  $S_{\tau} = \{w : w \in R^n, |w| \leq \tau, \tau > 0\}$  and

$S_{\kappa} = \{\mathfrak{U} : \mathfrak{U} \in R^n, |\mathfrak{U}| \leq \kappa, \kappa > 0\}$ , then for all  $\beta, \gamma, \delta \in C^n$  for each  $\Xi > 0$ , there exist a constant  $C_2 > 0$  and a positive integer  $\psi, \sigma, \xi \in I^+$  such that for  $0 < \Lambda \leq \frac{\pi}{2}$ , where  $I^+$  is the set of positive integer.

$$\begin{aligned} & |H_{\Lambda}(\beta, \gamma, \delta)| \\ & \leq C_2 \max_{\substack{\chi \leq \psi \\ \zeta \leq \sigma \\ \rho \leq \xi}} C_{\Lambda} C_{\Lambda}^* C_{\Lambda}^{**} \left[ \log(\varpi + \Xi_1) \right]^{A-U} \left[ \log(\varpi + \Xi_2) \right]^{B-R} \left[ \log(\varpi + \Xi_3) \right]^{M-L} \\ & C_U(\varpi + \Xi_1) C_R(\tau + \Xi_2) C_L(\kappa + \Xi_3) (\varpi + \Xi_1)^{\frac{\pi}{\sin \Lambda} \left[ 2(I_A \beta) + \cos \Lambda (I_A (\log(\varpi + \Xi_1))) \right] + U - \chi - 1} \\ & (\tau + \Xi_2)^{\frac{\pi}{\sin \Lambda} \left[ 2(I_B \gamma) + \cos \Lambda (I_B (\log(\tau + \Xi_2))) \right] + R - \zeta - 1} (\kappa + \Xi_3)^{\frac{\pi}{\sin \Lambda} \left[ 2(I_M \delta) + \cos \Lambda (I_M (\log(\kappa + \Xi_3))) \right] + L - \rho - 1}. \end{aligned}$$

**Proof.** By the Boundedness property of the generalized function, there exit a constant  $C_2$  and a positive integer  $\psi, \sigma$  and  $\xi$ , such that

$$\begin{aligned} & \left| H_{\Lambda}(\beta, \gamma, \delta) \right| \leq \left| \langle h(z, w, \mathfrak{U}), K_{\Lambda, \hbar, \mathfrak{S}}(z, w, \mathfrak{U}, \beta, \gamma, \delta) \rangle \right| \\ & \leq C_2 \max_{\substack{\chi \leq \psi \\ \zeta \leq \sigma \\ \rho \leq \xi}} \sup_{\substack{z \in R^n \\ w \in R^n \\ \mathfrak{U} \in R^n}} \left| D_z^{\chi} D_w^{\zeta} D_{\mathfrak{U}}^{\rho} K_{\Lambda}(z, w, \mathfrak{U}, \beta, \gamma, \delta) \right| \\ & \leq C_2 \max_{\substack{\chi \leq \psi \\ \zeta \leq \sigma \\ \rho \leq \xi}} \sup_{\substack{z \in R^n \\ w \in R^n \\ \mathfrak{U} \in R^n}} \left| \sum_{A=0}^{\chi} \sum_{U=0}^A \sum_{B=0}^{\zeta} \sum_{R=0}^B \sum_{M=0}^{\rho} \sum_{L=0}^M \binom{\chi}{A} \binom{\zeta}{B} \binom{\rho}{M} v(\beta) \Omega(\gamma) n(\delta) A! B! M! \right. \\ & \left. \frac{2\pi i \beta}{z \sin \Lambda}^{-1-\chi+U} \frac{2\pi i \gamma}{w \sin \Lambda}^{-1-\zeta+R} \frac{2\pi i \delta}{\mathfrak{U} \sin \Lambda}^{-1-\rho+L} \left( \frac{2\pi i}{\tan \Lambda} \right)^{A-U} \left( \frac{2\pi i}{\tan \Lambda} \right)^{B-R} \left( \frac{2\pi i}{\tan \Lambda} \right)^{M-L} \right| \\ & (\log z)^{A-U} (\log w)^{B-R} (\log \mathfrak{U})^{M-L} C_U(z) C_R(w) C_L(\mathfrak{U}) \\ & e^{\pi i \left[ \frac{1}{\tan \Lambda} (\beta^2 + \log^2 z) + \frac{1}{\tan \Lambda} (\gamma^2 + \log^2 w) + \frac{1}{\tan \Lambda} (\delta^2 + \log^2 \mathfrak{U}) \right]} \\ & \leq C_2 \max_{\substack{\chi \leq \psi \\ \zeta \leq \sigma \\ \rho \leq \xi}} C_{\Lambda} C_{\Lambda}^* C_{\Lambda}^{**} (\varpi + \Xi_1)^{\frac{2\pi(I_A \beta)}{\sin \Lambda} + U - \chi - 1} (\tau + \Xi_2)^{\frac{2\pi(I_B \gamma)}{\sin \Lambda} + R - \zeta - 1} \\ & (\kappa + \Xi_3)^{\frac{2\pi(I_M \delta)}{\sin \Lambda} + L - \rho - 1} [\log(\varpi + \Xi_1)]^{A-U} [\log(\tau + \Xi_2)]^{B-R} [\log(\kappa + \Xi_3)]^{M-L} \\ & C_U(\varpi + \Xi_1) C_R(\tau + \Xi_2) C_L(\kappa + \Xi_3) (\varpi + \Xi_1)^{\frac{\pi}{\tan \Lambda} (\varpi + \Xi_1)} (\tau + \Xi_2)^{\frac{\pi}{\tan \Lambda} (\tau + \Xi_2)} (\kappa + \Xi_3)^{\frac{\pi}{\tan \Lambda} (\kappa + \Xi_3)} \end{aligned}$$

$$\begin{aligned} \text{where, } C_\Lambda &= \sum_{A=0}^{\chi} \sum_{U=0}^A \binom{\chi}{A} A! R(\beta) \left(\frac{2\pi i}{\tan \Lambda}\right)^{A-U} e^{\frac{\pi(I_A \beta^2)}{\sin \Lambda}} \\ C_\Lambda^* &= \sum_{B=0}^{\zeta} \sum_{R=0}^B \binom{\zeta}{B} B! \hbar(\gamma) \left(\frac{2\pi i}{\tan \Lambda}\right)^{B-R} e^{\frac{\pi(I_B \gamma^2)}{\sin \Lambda}} \\ C_\Lambda^{**} &= \sum_{M=0}^{\rho} \sum_{L=0}^M \binom{\rho}{M} M! T(\delta) \left(\frac{2\pi i}{\tan \Lambda}\right)^{M-L} e^{\frac{\pi(I_M \delta^2)}{\sin \Lambda}} \end{aligned}$$

$$\begin{aligned} &\leq C_2 \max_{\substack{\chi \leq \psi \\ \zeta \leq \sigma \\ \rho \leq \xi}} C_\Lambda C_\Lambda^* C_\Lambda^{**} \left[ \log(\varpi + \Xi_1) \right]^{A-U} \left[ \log(\varpi + \Xi_2) \right]^{B-R} \left[ \log(\varpi + \Xi_3) \right]^{M-L} C_U(\varpi + \Xi_1) \\ &C_R(\tau + \Xi_2) C_L(\kappa + \Xi_3) (\varpi + \Xi_1) \frac{\pi}{\sin \Lambda} \left[ 2(I_A \beta) + \cos \Lambda (I_A (\log(\varpi + \Xi_1))) \right]^{+U-\chi-1} \\ &(\tau + \Xi_2) \frac{\pi}{\sin \Lambda} \left[ 2(I_B \gamma) + \cos \Lambda (I_B (\log(\tau + \Xi_2))) \right]^{+R-\zeta-1} (\kappa + \Xi_3) \frac{\pi}{\sin \Lambda} \left[ 2(I_M \delta) + \cos \Lambda (I_M (\log(\kappa + \Xi_3))) \right]^{+L-\rho-1}. \end{aligned}$$

Now we give inversion theorem in 3DFrMT.

**Theorem 2.4.** We can find the function  $h(z, w, \mathcal{U})$  using the inversion formula of 3DFrMT

$$h(z, w, \mathcal{U}) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H_\Lambda(\beta, \gamma, \delta) \tilde{K}_\Lambda(z, w, \mathcal{U}, \beta, \gamma, \delta) d\beta d\gamma d\delta,$$

where,

$$\begin{aligned} &\tilde{K}_\Lambda(z, w, \mathcal{U}, \beta, \gamma, \delta) \\ &= \left( \frac{-i}{\sin^3 \Lambda} \right) z \frac{-2\pi i \beta}{\sin \Lambda} w \frac{-2\pi i \gamma}{\sin \Lambda} \mathcal{U} \frac{-2\pi i \delta}{\sin \Lambda} e^{-\pi i \left[ \frac{1}{\tan \Lambda} (\beta^2 + \log^2 z) + \frac{1}{\tan \Lambda} (\gamma^2 + \log^2 w) + \frac{1}{\tan \Lambda} (\delta^2 + \log^2 \mathcal{U}) \right]}. \end{aligned}$$

**Proof.** We have

$$\begin{aligned} 3DFrMT\{h(z, w, \mathcal{U})\} &= H_\Lambda(\beta, \gamma, \delta) = \int_0^\infty \int_0^\infty \int_0^\infty h(z, w, \mathcal{U}) K_\Lambda(z, w, \mathcal{U}, \beta, \gamma, \delta) dz dw d\mathcal{U} \\ &= \int_0^\infty \int_0^\infty \int_0^\infty h(z, w, \mathcal{U}) z \frac{2\pi i \beta}{\sin \Lambda}^{-1} w \frac{2\pi i \gamma}{\sin \Lambda}^{-1} \mathcal{U} \frac{2\pi i \delta}{\sin \Lambda}^{-1} \end{aligned}$$

$$e^{\pi i \left[ \frac{1}{\tan \Lambda} (\beta^2 + \log^2 z) + \frac{1}{\tan \Lambda} (\gamma^2 + \log^2 w) + \frac{1}{\tan \Lambda} (\delta^2 + \log^2 \mathcal{U}) \right]} dz dw d\mathcal{U}.$$

$$\therefore \frac{-\pi i \beta^2}{e \tan \Lambda} \frac{-\pi i \gamma^2}{e \tan \Lambda} \frac{-\pi i \delta^2}{e \tan \Lambda} H_{\Lambda}(\beta, \gamma, \delta)$$

$$= \int_0^{\infty} \int_0^{\infty} \int_0^{\infty} h(z, w, \mathcal{U}) z^{\frac{2\pi i \beta}{\sin \Lambda} - 1} w^{\frac{2\pi i \gamma}{\sin \Lambda} - 1} \mathcal{U}^{\frac{2\pi i \delta}{\sin \Lambda} - 1} e^{\pi i \left[ \frac{\log^2 z}{\tan \Lambda} + \frac{\log^2 w}{\tan \Lambda} + \frac{\log^2 \mathcal{U}}{\tan \Lambda} \right]} dz dw d\mathcal{U}$$

$$= \int_0^{\infty} \int_0^{\infty} \int_0^{\infty} g(z, w, \mathcal{U}) z^{\frac{2\pi i \beta}{\sin \Lambda} - 1} w^{\frac{2\pi i \gamma}{\sin \Lambda} - 1} \mathcal{U}^{\frac{2\pi i \delta}{\sin \Lambda} - 1} dz dw d\mathcal{U},$$

where,

$$g(z, w, \mathcal{U}) = h(z, w, \mathcal{U}) e^{\pi i \left[ \frac{\log^2 z}{\tan \Lambda} + \frac{\log^2 w}{\tan \Lambda} + \frac{\log^2 \mathcal{U}}{\tan \Lambda} \right]}$$

$$= M\{g(z, w, \mathcal{U})\} (\tau) (\Omega) (\Psi),$$

$$\text{where, } \tau = \left( \frac{2\pi i \beta}{\sin \Lambda} \right), \Omega = \left( \frac{2\pi i \gamma}{\sin \Lambda} \right), \Psi = \left( \frac{2\pi i \delta}{\sin \Lambda} \right).$$

Using inverse Mellin transform

$$g(z, w, \mathcal{U}) = \frac{1}{8\pi^3} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} G(\tau, \Omega, \Psi) z^{-\tau} w^{-\Omega} \mathcal{U}^{-\Psi} d\tau d\Omega d\Psi,$$

where,

$$G(\tau, \Omega, \Psi) = e^{\frac{-\pi i \beta^2}{\tan \Lambda}} e^{\frac{-\pi i \gamma^2}{\tan \Lambda}} e^{\frac{-\pi i \delta^2}{\tan \Lambda}} H_{\Lambda} \left( \frac{\tau \sin \Lambda}{2\pi i}, \frac{\Omega \sin \Lambda}{2\pi i}, \frac{\Psi \sin \Lambda}{2\pi i} \right)$$

$$\therefore h(z, w, \mathcal{U}) e^{\pi i \left[ \frac{\log^2 z}{\tan \Lambda} + \frac{\log^2 w}{\tan \Lambda} + \frac{\log^2 \mathcal{U}}{\tan \Lambda} \right]} = \frac{1}{8\pi^3} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} G(\tau, \Omega, \Psi) z^{-\tau} w^{-\Omega} \mathcal{U}^{-\Psi} d\tau d\Omega d\Psi$$

$$\therefore h(z, w, \mathcal{U}) = \frac{1}{8\pi^3} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{\frac{-\pi i \beta^2}{\tan \Lambda}} e^{\frac{-\pi i \gamma^2}{\tan \Lambda}} e^{\frac{-\pi i \delta^2}{\tan \Lambda}} H_{\Lambda, \hbar, \mathfrak{S}}(\beta, \gamma, \delta) z^{-\frac{2\pi i \beta}{\sin \Lambda}} w^{-\frac{2\pi i \gamma}{\sin \Lambda}}$$



$$\begin{aligned} & \mathfrak{U}^{\frac{-2\pi i\delta}{\sin \Lambda}} \left(\frac{2\pi i}{\sin \Lambda}\right) \left(\frac{2\pi i}{\sin \Lambda}\right) \left(\frac{2\pi i}{\sin \Lambda}\right) e^{-\pi i \left[\frac{\log^2 z}{\tan \Lambda} + \frac{\log^2 w}{\tan \Lambda} + \frac{\log^2 \mathfrak{U}}{\tan \Lambda}\right]} d\beta d\gamma d\delta \\ h(z, w, \mathfrak{U}) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H_{\Lambda}(\beta, \gamma, \delta) \tilde{K}_{\Lambda}(z, w, \mathfrak{U}, \beta, \gamma, \delta) d\beta d\gamma d\delta \end{aligned}$$

where,

$$\begin{aligned} & \tilde{K}_{\Lambda}(z, w, \mathfrak{U}, \beta, \gamma, \delta) \\ &= \left(\frac{-i}{\sin^3 \Lambda}\right) z^{\frac{-2\pi i\beta}{\sin \Lambda}} w^{\frac{-2\pi i\gamma}{\sin \Lambda}} \mathfrak{U}^{\frac{-2\pi i\delta}{\sin \Lambda}} e^{-\pi i \left[\frac{1}{\tan \Lambda}(\beta^2 + \log^2 z) + \frac{1}{\tan \Lambda}(\gamma^2 + \log^2 w) + \frac{1}{\tan \Lambda}(\delta^2 + \log^2 \mathfrak{U})\right]}. \end{aligned}$$

Now we give uniqueness theorem in 3DFrMT.

**Theorem 2.5.** If  $H_{\Lambda}(\beta, \gamma, \delta) = \text{3DFrMT} \{h(z, w, \mathfrak{U})\}$ ,  $G_{\Lambda}(\beta, \gamma, \delta) = \text{3DFrMT} \{g(z, w, \mathfrak{U})\}$ ,

$Q_{\Lambda}(\beta, \gamma, \delta) = \text{3DFrMT} \{q(z, w, \mathfrak{U})\}$  for,  $0 < \Lambda \leq \frac{\pi}{2}$  and  $\text{supp } h \subset S_{\varpi}$ ,  $\text{supp } g \subset S_{\tau}$ ,  $\text{supp } q \subset S_{\kappa}$ , where

$$S_{\varpi} = \{z : z \in R^n, |z| \leq \varpi, \varpi > 0\},$$

$$S_{\tau} = \{w : w \in R^n, |w| \leq \tau, \tau > 0\},$$

$$S_{\kappa} = \{\mathfrak{U} : \mathfrak{U} \in R^n, |\mathfrak{U}| \leq \kappa, \kappa > 0\}.$$

If,  $H_{\Lambda}(\beta, \gamma, \delta) = G_{\Lambda}(\beta, \gamma, \delta) = Q_{\Lambda}(\beta, \gamma, \delta)$  then  $h = g = q$  in the sense of equality in  $E^*$ .

**Proof.** By inversion theorem

$$\begin{aligned} & h - g - q \\ &= \lim_{M \rightarrow \infty} \frac{1}{2\pi} \int_{-M}^M \tilde{K}_{\Lambda}(z, w, \mathfrak{U}, \beta, \gamma, \delta) \left[ H_{\Lambda}(\beta, \gamma, \delta) - G_{\Lambda}(\beta, \gamma, \delta) - Q_{\Lambda}(\beta, \gamma, \delta) \right] d\beta d\gamma d\delta \\ &= 0. \end{aligned}$$

### 3 Some Propositions

**Example 3.1.** Show that

$$\{3DFrMT(1)\}(\beta, \gamma, \delta) = (i \tan \Lambda)^{3/2} e^{-\pi i \tan \Lambda (\beta^2 + \gamma^2 + \delta^2)}$$

**Proof.** We have  $\{3DFrMT(1)\}(\beta, \gamma, \delta)$

$$= \int_0^\infty \int_0^\infty \int_0^\infty (1) \frac{2\pi i \beta}{z \sin \Lambda}^{-1} \frac{2\pi i \gamma}{w \sin \Lambda}^{-1} \frac{2\pi i \delta}{\mathcal{U} \sin \Lambda}^{-1} \frac{\pi i}{e \tan \Lambda}^{(\beta^2 + \gamma^2 + \delta^2 + \log^2 z + \log^2 w + \log^2 \mathcal{U})} dz dw d\mathcal{U}$$

putting,

$$\log z = \varpi \implies z = e^\varpi \implies dz = e^\varpi d\varpi$$

$$\log w = \nu \implies w = e^\nu \implies dw = e^\nu d\nu$$

$$\log \mathcal{U} = \psi \implies \mathcal{U} = e^\psi \implies d\mathcal{U} = e^\psi d\psi$$

$$\therefore \{3DFrMT(1)\}(\beta, \gamma, \delta)$$

$$= \int_{-\infty}^\infty \int_{-\infty}^\infty \int_{-\infty}^\infty (e^\varpi)^{\frac{2\pi i \beta}{\sin \Lambda}^{-1}} (e^\nu)^{\frac{2\pi i \gamma}{\sin \Lambda}^{-1}} (e^\psi)^{\frac{2\pi i \delta}{\sin \Lambda}^{-1}} \frac{\pi i}{e \tan \Lambda}^{(\beta^2 + \gamma^2 + \delta^2 + \varpi^2 + \nu^2 + \psi^2)} e^\varpi e^\nu e^\psi d\varpi d\nu d\psi$$

$$\text{where, } X = \frac{2\pi}{\sin \Lambda}, Y = \frac{\pi}{\tan \Lambda}$$

$$= e^{\frac{\pi i}{\tan \Lambda} (\beta^2 + \gamma^2 + \delta^2)} \int_{-\infty}^\infty \int_{-\infty}^\infty \int_{-\infty}^\infty e^{iX(\beta\varpi + \gamma\nu + \delta\psi)} e^{iY(\varpi^2 + \nu^2 + \psi^2)} d\varpi d\nu d\psi$$

$$= \left(\frac{\pi i}{Y}\right)^{3/2} e^{i\left\{\frac{\pi}{\tan \Lambda} - \frac{X^2}{4Y}\right\}(\beta^2 + \gamma^2 + \delta^2)}$$

$$= (i \tan \Lambda)^{3/2} e^{-\pi i \tan \Lambda (\beta^2 + \gamma^2 + \delta^2)}.$$

**Example 3.2.** Show that

$$\left\{3DFrMT\left(e^{i[\zeta(\log m)^2 + \xi(\log n)^2 + \psi(\log l)^2]}\right)\right\}(\beta, \gamma, \delta)$$

$$= \frac{(\pi i)^{3/2}}{\sqrt{XYZ}} e^{\frac{\pi i}{\tan \Lambda} (\beta^2 + \gamma^2 + \delta^2)} \frac{-i\pi^2}{e \sin \Lambda \cos \Lambda} \left\{ \frac{\beta^2}{\pi + \zeta \tan \Lambda} + \frac{\gamma^2}{\pi + \xi \tan \Lambda} + \frac{\delta^2}{\pi + \psi \tan \Lambda} \right\}$$

**Proof.** We have

$$\begin{aligned}
& \left\{ 3DFrMT \left( e^{i [\zeta \log^2 m + \xi \log^2 n + \psi \log^2 l]} \right) \right\} (\beta, \gamma, \delta) \\
&= \int_0^\infty \int_0^\infty \int_0^\infty \left[ e^{i [\zeta \log^2 m + \xi \log^2 n + \psi \log^2 l]} \right] m^{\frac{2\pi i \beta}{\sin \Lambda} - 1} n^{\frac{2\pi i \gamma}{\sin \Lambda} - 1} l^{\frac{2\pi i \delta}{\sin \Lambda} - 1} \\
&\quad e^{\frac{\pi i}{\tan \Lambda} (\beta^2 + \gamma^2 + \delta^2 + \log^2 m + \log^2 n + \log^2 l)} dm \, dn \, dl \\
&= \int_0^\infty \int_0^\infty \int_0^\infty \frac{2\pi i \beta}{m \sin \Lambda}^{-1} \frac{2\pi i \gamma}{n \sin \Lambda}^{-1} \frac{2\pi i \delta}{l \sin \Lambda}^{-1} \frac{\pi i}{e \tan \Lambda}^{(\beta^2 + \gamma^2 + \delta^2)} e^{i(\zeta \log^2 m + \xi \log^2 n + \psi \log^2 l)} \\
&\quad \frac{\pi i}{e \tan \Lambda}^{(\log^2 m + \log^2 n + \log^2 l)} dm \, dn \, dl
\end{aligned}$$

Putting,

$$\log m = A \Rightarrow m = e^A \Rightarrow dm = e^A dA$$

$$\log n = B \Rightarrow n = e^B \Rightarrow dn = e^B dB$$

$$\log l = C \Rightarrow l = e^C \Rightarrow dl = e^C dC$$

$$\begin{aligned}
& \therefore \left\{ 3DFrMT \left( e^{i[\zeta \log^2 m + \xi \log^2 n + \psi \log^2 l]} \right) \right\} (\beta, \gamma, \delta) \\
&= e^{\frac{\pi i}{\tan \Lambda} (\beta^2 + \gamma^2 + \delta^2)} \int_{-\infty}^\infty \int_{-\infty}^\infty \int_{-\infty}^\infty (e^A)^{\frac{2\pi i \beta}{\sin \Lambda}} (e^B)^{\frac{2\pi i \gamma}{\sin \Lambda}} (e^C)^{\frac{2\pi i \delta}{\sin \Lambda}} \\
&\quad e^{i \left[ \left( \zeta + \frac{\pi}{\tan \Lambda} \right) A^2 + \left( \xi + \frac{\pi}{\tan \Lambda} \right) B^2 + \left( \psi + \frac{\pi}{\tan \Lambda} \right) C^2 \right]} dA \, dB \, dC \\
&= e^{\frac{\pi i}{\tan \Lambda} (\beta^2 + \gamma^2 + \delta^2)} \int_{-\infty}^\infty e^{iGA + iXA^2} dA \int_{-\infty}^\infty e^{iHB + iYB^2} dB \int_{-\infty}^\infty e^{iLC + iZC^2} dC
\end{aligned}$$

where,

$$G = \frac{2\pi\beta}{\sin \Lambda}, \quad H = \frac{2\pi\gamma}{\sin \Lambda}, \quad L = \frac{2\pi\delta}{\sin \Lambda}, \quad X = \zeta + \frac{\pi}{\tan \Lambda}, \quad Y = \xi + \frac{\pi}{\tan \Lambda}, \quad Z = \psi + \frac{\pi}{\tan \Lambda}$$

$$\therefore \left\{ 3DFrMT \left( e^{i[\zeta \log^2 m + \xi \log^2 n + \psi \log^2 l]} \right) \right\} (\beta, \gamma, \delta)$$

$$\begin{aligned}
&= e^{\frac{\pi i}{\tan \Lambda}(\beta^2+\gamma^2+\delta^2)} \int_{-\infty}^{\infty} e^{iGA+iXA^2} dA \int_{-\infty}^{\infty} e^{iHB+iYB^2} dB \int_{-\infty}^{\infty} e^{iLA+iZA^2} dC \\
&= \frac{(\pi i)^{3/2}}{\sqrt{XYZ}} e^{\frac{\pi i}{\tan \Lambda}(\beta^2+\gamma^2+\delta^2)} \frac{-i\pi^2}{\sin^2 \Lambda} \tan \Lambda \left\{ \frac{\beta^2}{\pi + \zeta \tan \Lambda} + \frac{\gamma^2}{\pi + \xi \tan \Lambda} + \frac{\delta^2}{\pi + \psi \tan \Lambda} \right\} \\
&\therefore \left\{ 3DFrMT \left( e^{i[\zeta (\log m)^2 + \xi (\log n)^2 + \psi (\log l)^2]} \right) \right\} (\beta, \gamma, \delta) \\
&= \frac{(\pi i)^{3/2}}{\sqrt{XYZ}} e^{\frac{\pi i}{\tan \Lambda}(\beta^2+\gamma^2+\delta^2)} \frac{-i\pi^2}{\sin \Lambda \cos \Lambda} \left\{ \frac{\beta^2}{\pi + \zeta \tan \Lambda} + \frac{\gamma^2}{\pi + \xi \tan \Lambda} + \frac{\delta^2}{\pi + \psi \tan \Lambda} \right\}.
\end{aligned}$$

## 4 Applications

**Application 4.1.** Let us Consider the Mboctara PDE's

$$\partial_{xyt} \hbar(x, y, t) + \hbar(x, y, t) = 0. \quad (4.1)$$

Using the proposed transform, we have

$$\begin{aligned}
&(-1) \left( \frac{2\pi i \beta}{\sin \Lambda} - 1 \right) H_{\Lambda}(\beta - 1) (-1) \left( \frac{2\pi i \gamma}{\sin \Lambda} - 1 \right) H_{\Lambda}(\gamma - 1) (-1) \left( \frac{2\pi i \delta}{\sin \Lambda} - 1 \right) H_{\Lambda}(\delta - 1) \\
&+ \hbar(z, w, \mathcal{U}) = 0
\end{aligned}$$

$$\text{or, } \hbar(z, w, \mathcal{U}) = \left( \frac{2\pi i \beta}{\sin \Lambda} - 1 \right) H_{\Lambda} \left( \frac{2\pi i \gamma}{\sin \Lambda} - 1 \right) H_{\Lambda} \left( \frac{2\pi i \delta}{\sin \Lambda} - 1 \right) \left[ H_{\Lambda}(\beta - 1), H_{\Lambda}(\gamma - 1), H_{\Lambda}(\delta - 1) \right]$$

$$\begin{aligned}
\hbar(x, y, t) = -FrMT^{-1} \left\{ \left[ \left( \frac{2\pi i \beta}{\sin \Lambda} - 1 \right) \left( \frac{2\pi i \gamma}{\sin \Lambda} - 1 \right) \left( \frac{2\pi i \delta}{\sin \Lambda} - 1 \right) \right] \right. \\
\left. \left[ H_{\Lambda}(\beta - 1), H_{\Lambda}(\gamma - 1), H_{\Lambda}(\delta - 1) \right] \right\}.
\end{aligned}$$

**Application 4.2.** Let us consider the Mboctara PDE's

$$\partial_{xyt} \hbar(x, y, t) + \hbar(x, y, t) = 1. \quad (4.2)$$

Using the proposed transform, we have

$$\begin{aligned}
& (-1) \left( \frac{2\pi i\beta}{\sin \Lambda} - 1 \right) H_\Lambda(\beta - 1) \quad (-1) \left( \frac{2\pi i\gamma}{\sin \Lambda} - 1 \right) H_\Lambda(\gamma - 1) \quad (-1) \left( \frac{2\pi i\delta}{\sin \Lambda} - 1 \right) H_\Lambda(\delta - 1) \\
& + \hbar(z, w, \mathcal{U}) = (i \tan \Lambda)^{3/2} e^{-\pi i \tan \Lambda (\beta^2 + \gamma^2 + \delta^2)} \\
\text{or, } \hbar(z, w, \mathcal{U}) &= \frac{(i \tan \Lambda)^{3/2} e^{-\pi i \tan \Lambda (\beta^2 + \gamma^2 + \delta^2)}}{\left[ \left( \frac{2\pi i\beta}{\sin \Lambda} - 1 \right) \left( \frac{2\pi i\gamma}{\sin \Lambda} - 1 \right) \left( \frac{2\pi i\delta}{\sin \Lambda} - 1 \right) \right] \left[ H_\Lambda(\beta - 1), H_\Lambda(\gamma - 1), H_\Lambda(\delta - 1) \right]} \\
\hbar(x, y, t) &= FrMT^{-1} \left\{ \frac{(i \tan \Lambda)^{3/2} e^{-\pi i \tan \Lambda (\beta^2 + \gamma^2 + \delta^2)}}{\left[ \left( \frac{2\pi i\beta}{\sin \Lambda} - 1 \right) \left( \frac{2\pi i\gamma}{\sin \Lambda} - 1 \right) \left( \frac{2\pi i\delta}{\sin \Lambda} - 1 \right) \right] \left[ H_\Lambda(\beta - 1), H_\Lambda(\gamma - 1), H_\Lambda(\delta - 1) \right]} \right\}.
\end{aligned}$$

### Discussion

The Mellin transform is applicable in different branches of science and engineering for analyzing the algorithms of any system because it is a scale co-variant transform. Since fractional Mellin transform is a generalization of Mellin transform, it is applicable to control the range of rotation and scaling of any signal system. Three dimensional fractional Mellin transform can split the signal into fractional form signals, so its analysis can be more accurate and comfortable than a compact one in the extraction and separation of the image of any system. The present work generalizes the current state of knowledge in our topic because this work is wrathful in more general as in three-dimensional scenarios. The work of three-dimensional fractional Mellin transform and its applications is a novel work in the field of integral transform due to it aids generalized tools with three dimensional to solve more complicated problems. The results represent pioneer importance previously untouched in the field of extension fractionally for the Mellin transform.

### Conclusion

Finally, in this paper, we have generalized the three dimensional fractional Mellin transform in the distributional sense and proved its analytic theorem, boundedness theorem, inversion theorem, and uniqueness theorem. Also, we have given propositions of 3-DFrMT, which can also be applied with advantages to solve the different types of problems in any signal processing system, especially in a navigational system as a co-relator to control moments in any specific three-dimensional space.

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